

## Probabilistic approach and active perception

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### ■ Team overview

We are interested in three dimensional object perception. More specifically, our research focuses on the way the set of sensory-motor information is integrated by the brain to elaborate a coherent representation of objects and of their geometrical properties. Our working hypothesis is that perception - in particular the visual perception - cannot be understood in isolation; the perception is always guided and modified by subject's action. As a consequence, we are also investigating several aspects of motor control and action planning. These studies give us insight on how perception, i.e. representations extracted from sensory-motor information, can be pertinent for action. Our methods include psychophysical experiments, brain functional imagery, modelling and simulation works performed in collaboration with robotics labs.

### ■ Techniques used

Psychophysics and experimental psychology,  
Mathematical modelling and robotics,  
Functional neuroimaging

### ■ Bibliography

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## ■ Website

<http://www.lppa.college-de-france.fr/>